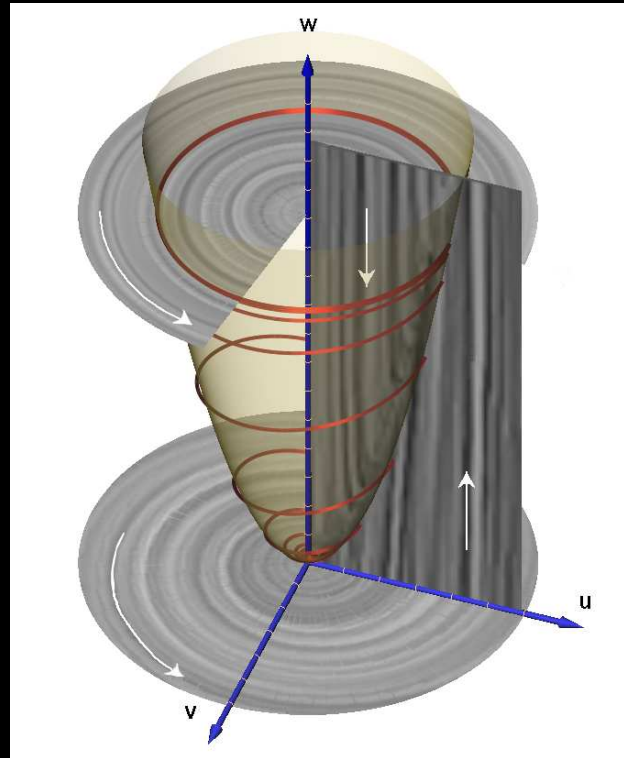
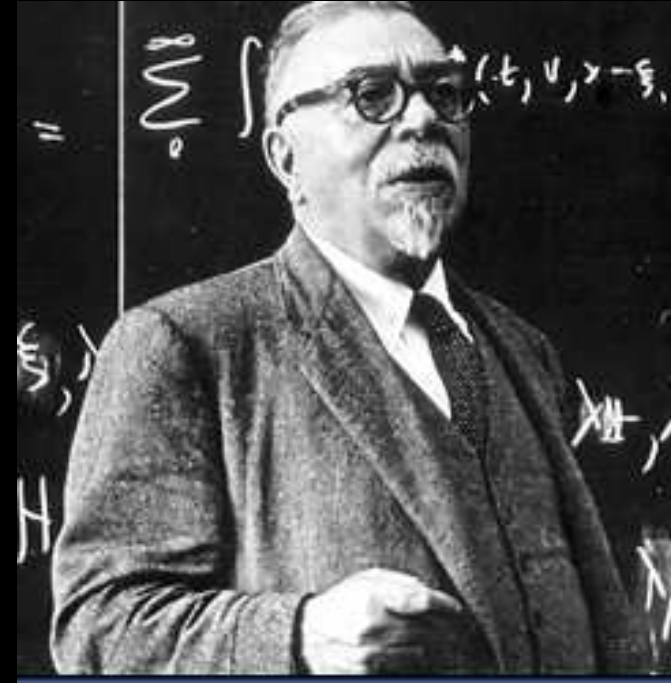
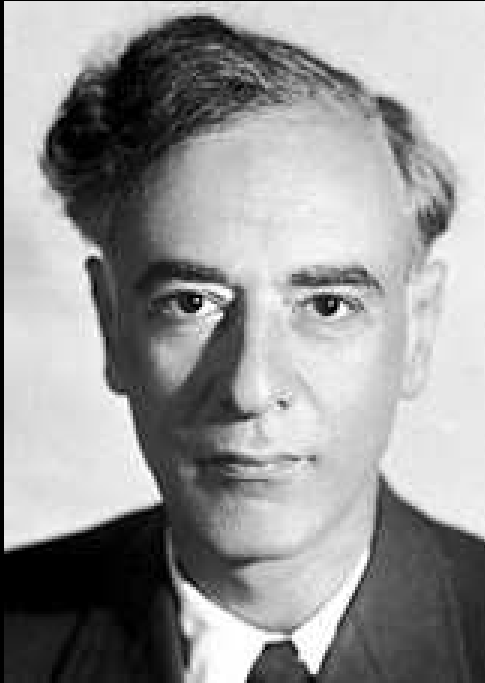


Low-dimensional modelling — Towards attractor control *I*



Bernd R. Noack & friends
Berlin Institute of Technology & elsewhere

Low-dimensional modelling — Towards attractor control



Bernd R. Noack

Berlin Institute of Technology

& friends

& elsewhere

Bernd's friends

— subset for FTT ordered by distance from my office

at the Berlin Institute of Technology



Michael
Schlegel



Mark
Luchtenburg



Mark
Pastoor



Rudibert
King

and elsewhere



Gerd
Mutschke



Marek
Morzyński



Pierre
Comte



Gilead
Tadmor



Boye
Ahlborn



My lectures

- 1 (Mo) Motivation of Galerkin method, 2 examples
- 2 (Tu) Empirical Galerkin method based on POD
- 3 (Tu) POD-based Galerkin models of natural flow

4+5

Towards a attractor control

(Th)

Purpose of this lecture:

- Make you excited about Galerkin modelling
- by connecting to (non)linear dynamics, statistical physics and cybernetics
- and by sketching a flow control of the future.

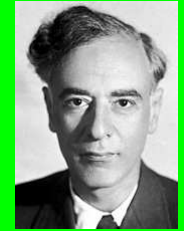
Overview

1. Introduction

..... *physics & cybernetics dreams revisited*

2. Mean-field modelling

..... *complete order / stability theory*



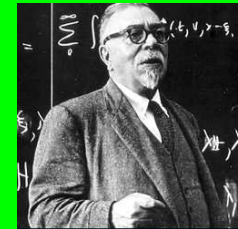
3. Attractor modelling

..... *complete disorder / statistical physics*



4. Attractor control

..... *Maxwellian and other deamons*



5. Summary and outlook

Overview

1. Introduction

..... *physics & cybernetics dreams revisited*

2. Mean-field modelling

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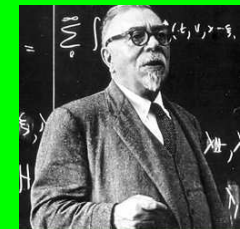
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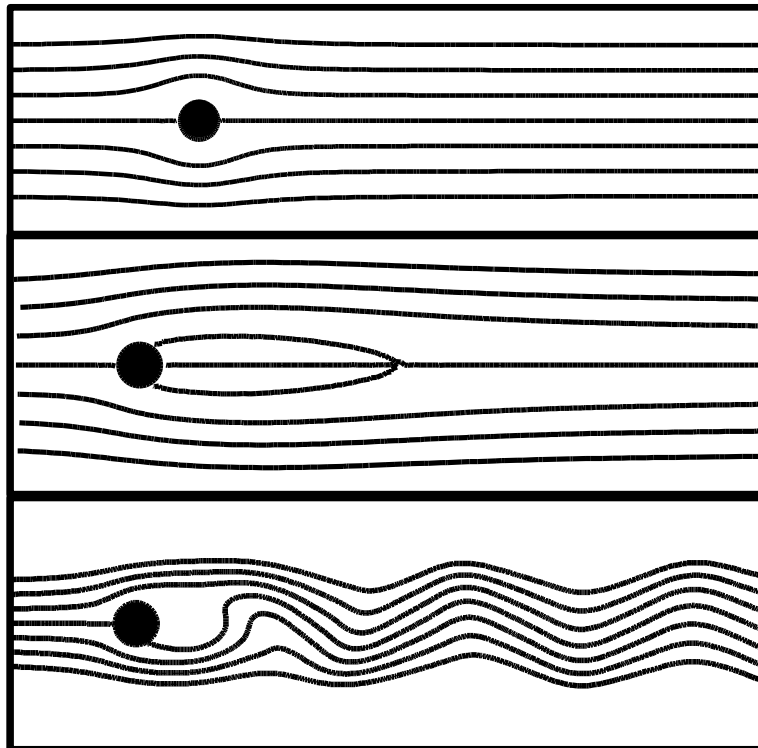


5. Summary and outlook

Phenomenogram of cylinder wake

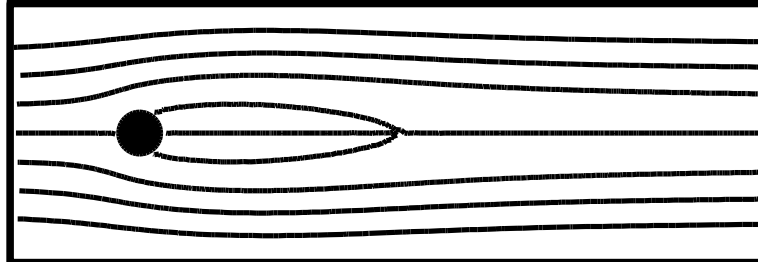
Reynolds number $Re = \frac{UD}{\nu}$

$Re < 4$



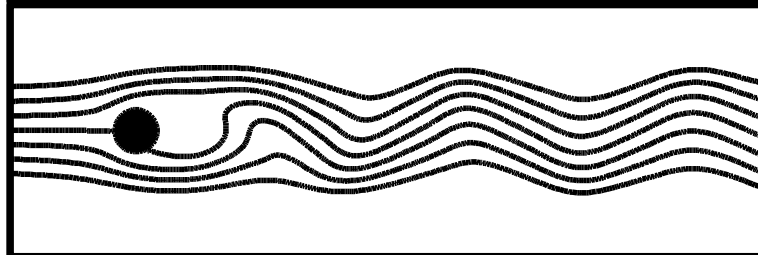
2D steady flow
without vortex pair

$Re < 47$



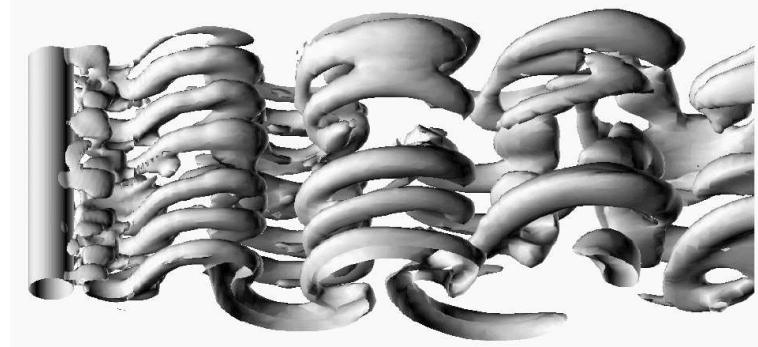
2D steady flow
with vortex pair

$Re < 180$



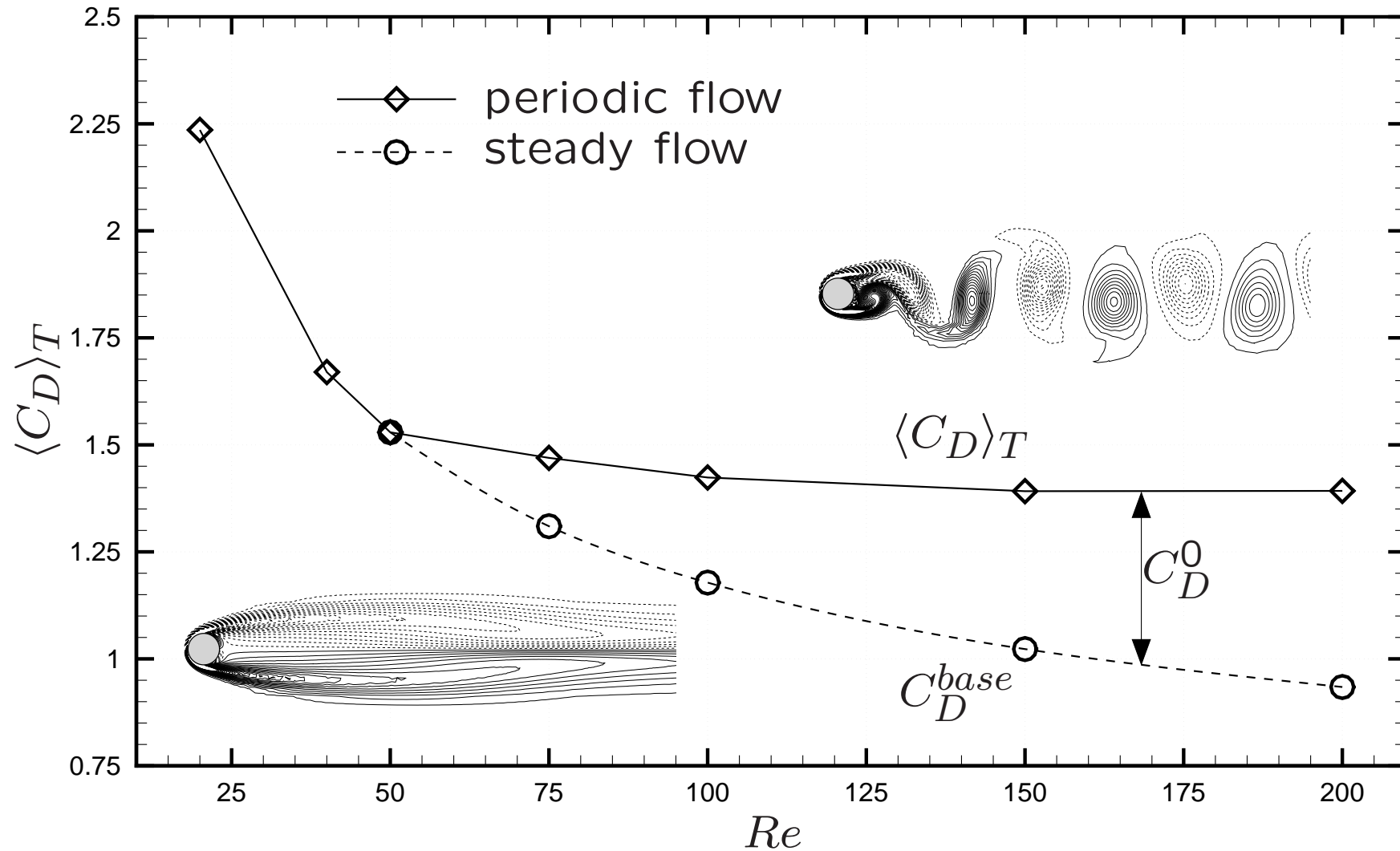
2D vortex shedding

$180 < Re$



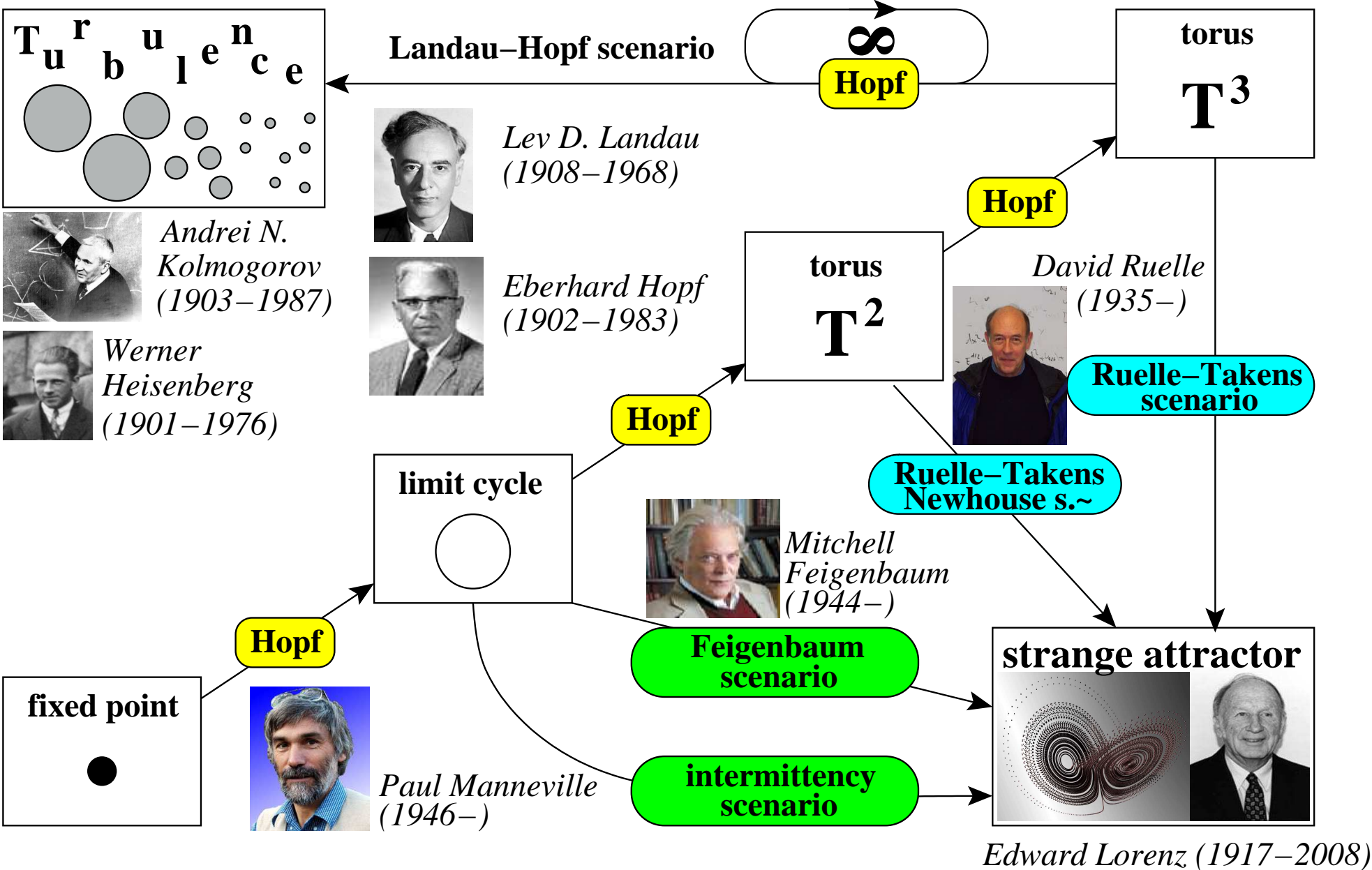
2D vortex shedding
superimposed by 3D
modes / fluctuations

Drag of cylinder wake



From Protas & Wesfreid 2002 *Phys. Fluids*

Dream #1: Instabilities \mapsto turbulence



Dream #2: Statistical physics \mapsto turbulence

Ludwig Boltzmann

(1840–1906)

**Equivalent
subsystems:**

1877: Entropy

$$S = k \ln W$$



Lars Onsager

(1903–1976)

**Particle/vortex
picture:**

1949: point vortices

in 2D flows

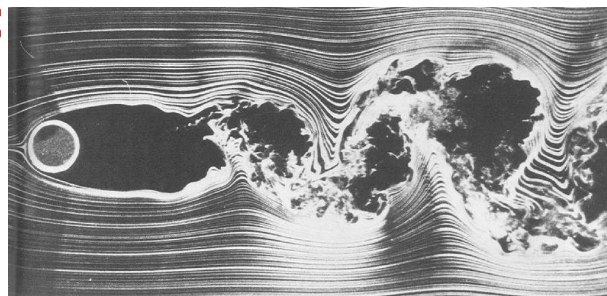
= thermodyn. degree of freedom



Hans W Liepmann (1914-)'s

WARNING:

Don't
forget \rightarrow



Robert H Kraichnan

(1928–2008)

Wave/Galerkin picture:

1955: Fourier modes

= thermodyn. degrees of freedom

(absolute equilibrium ensemble)



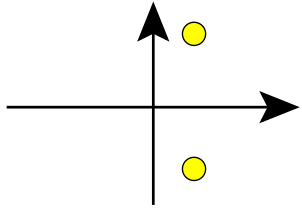
How to partition the flow in equivalent subsystems (atoms)

(= thermodynamic degrees of freedom)???

Dream #3: Control \mapsto turbulence

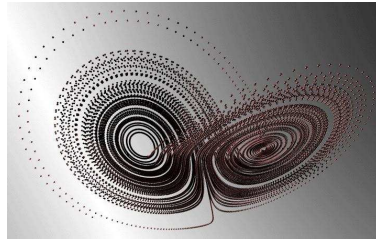
linear dynamics

$$da/dt = A a + B b$$



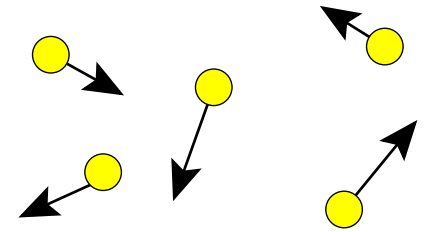
strange attractor

$$da/dt = f(a,b)$$



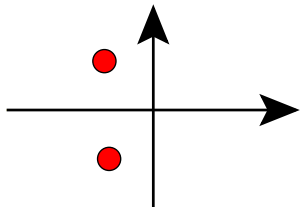
statistical physics

$$S = k \ln W$$

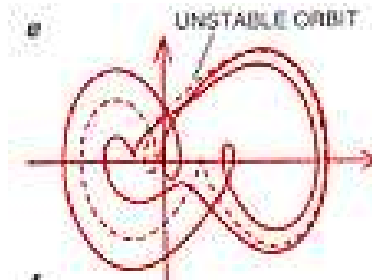


linear control

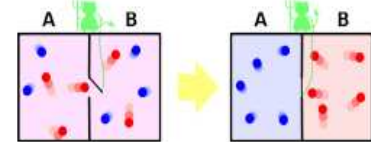
$$b = K a$$



chaos control



Maxwell's demon



Anno
Dazumal

Ott, Grebogi, Yorke
1990 PRL

Maxwell 1867
Wiener 1948

Turbulence control \mapsto transport vehicles

linear dynamics
 $da/dt = A a + B b$

strange attractor
 $da/dt = f(a,b)$

statistical physics
 $S = k \ln W$

linear control
 $b = K a$

chaos control

Maxwell's demon

Anno
Dazumal

Ott, Grebogi, Yorke
1990 PRL

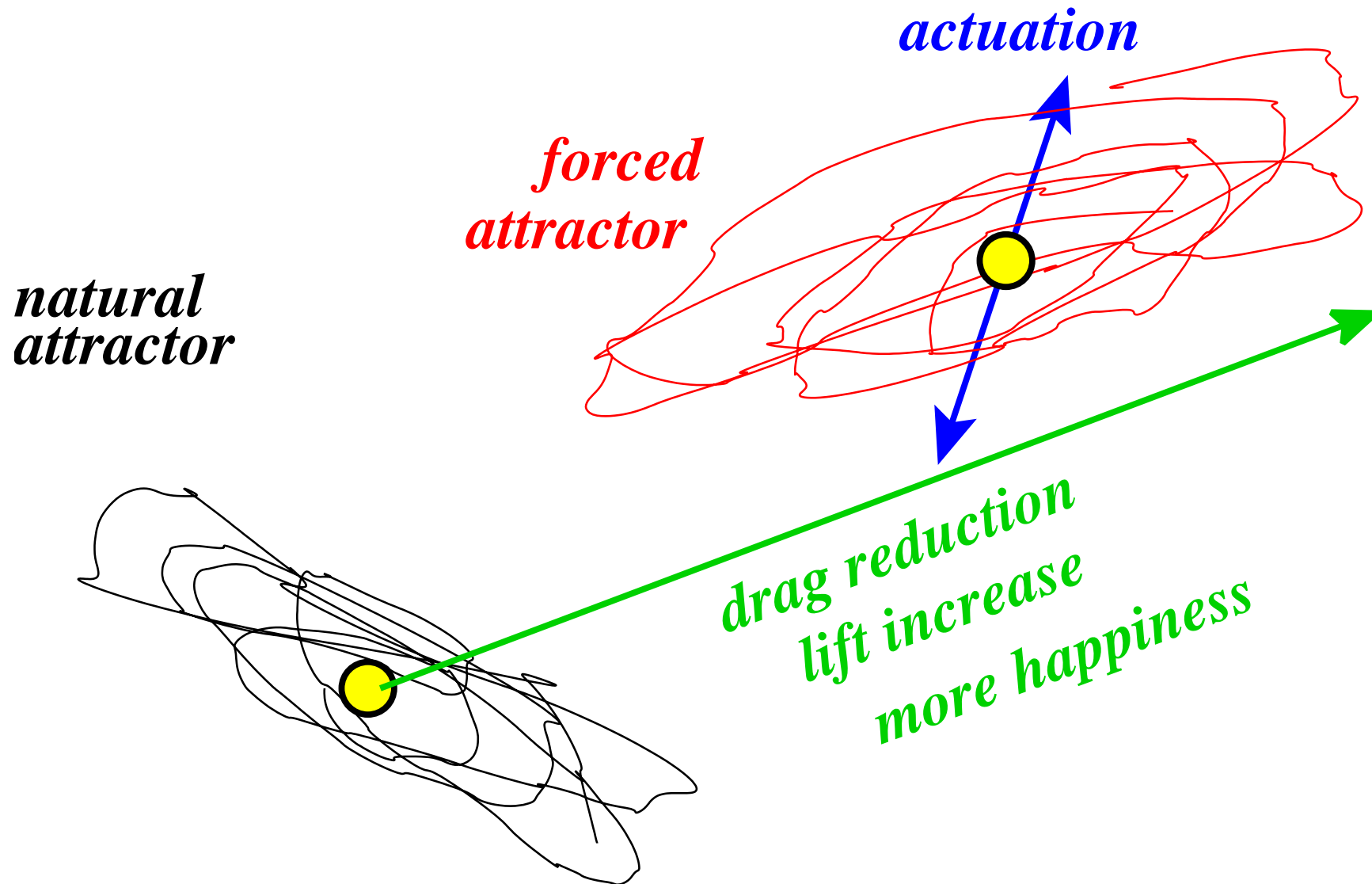
Maxwell 1867
Wiener 1948



Promising modelling and control methods for practical applications?

Turbulence control = attractor control

Phase space



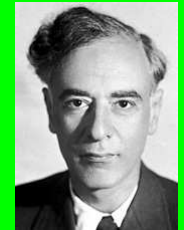
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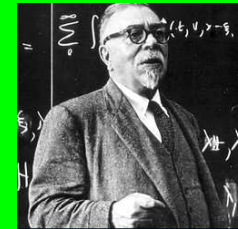
3. Attractor modelling

..... *complete disorder / statistical physics*



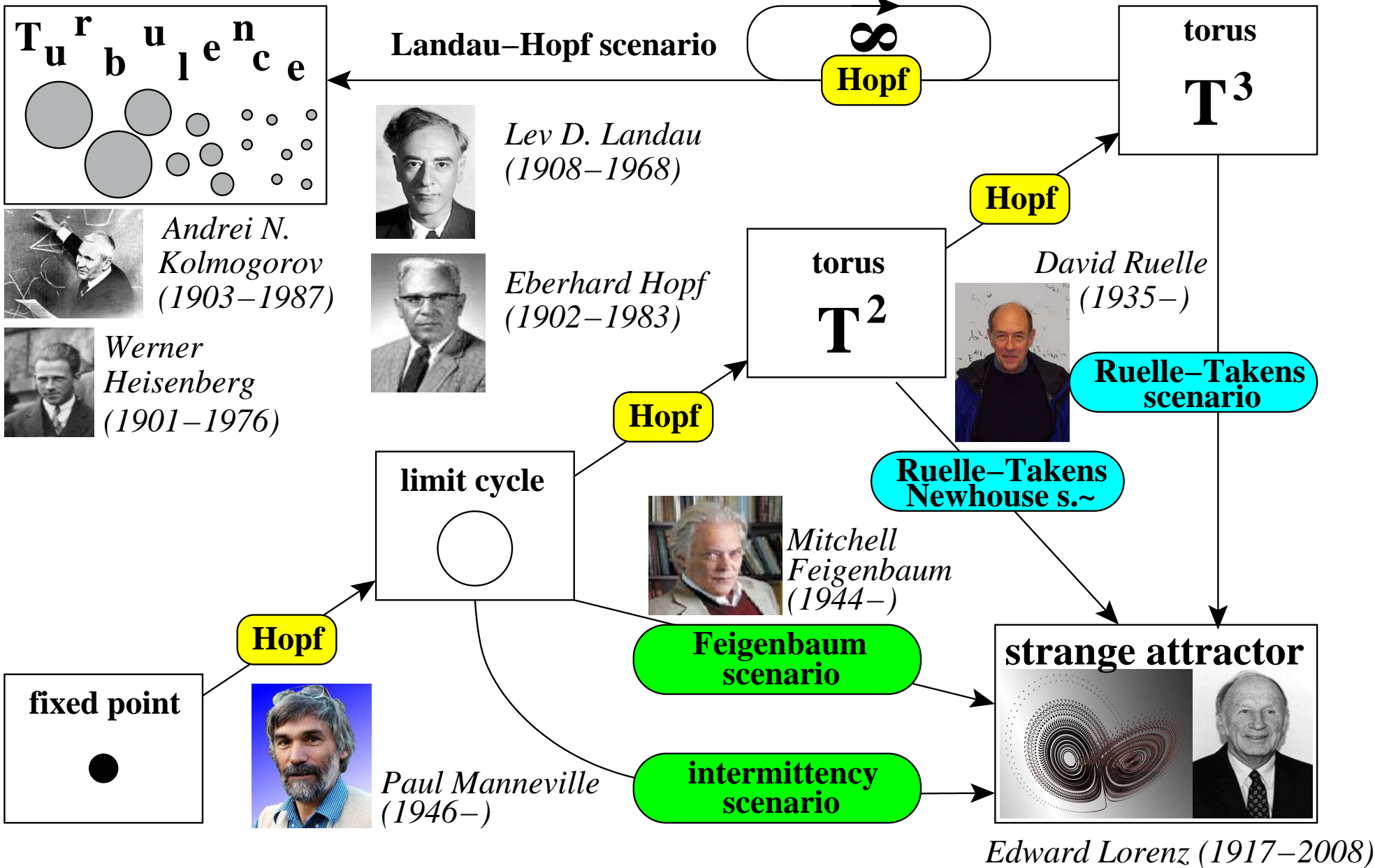
4. Attractor control

..... *Maxwellian and other deamons*



5. Summary and outlook

Dream #1: Instabilities \mapsto turbulence

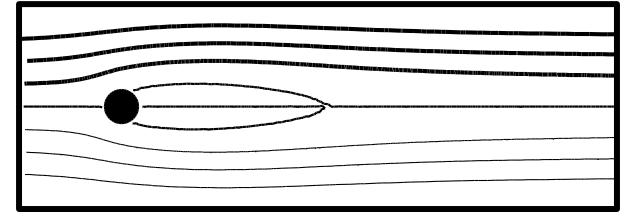


Global linear stability analysis

—  Noack, Afanasiev, Morzyński, Tadmor & Thiele (2003) JFM —

(Unstable) steady Navier-Stokes solution at $Re = 100$

$$\nabla \cdot (\mathbf{u}_s \mathbf{u}_s) = -\nabla p_s + \nu \Delta \mathbf{u}_s$$



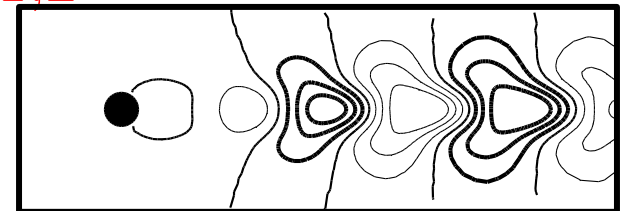
Linearized Navier-Stokes equation $\mathbf{u} = \mathbf{u}_s + \mathbf{u}'$

$$\partial_t \mathbf{u}' + \nabla \cdot (\mathbf{u}_s \mathbf{u}' + \mathbf{u}' \mathbf{u}_s) = -\nabla p' + \nu \Delta \mathbf{u}'$$

Instability described by normal mode $\lambda_{1,2} = 0.139 \pm i0.855$

$$\mathbf{u}' \sim e^{\lambda_{1,2} t} \mathbf{f}_1(\mathbf{x})$$

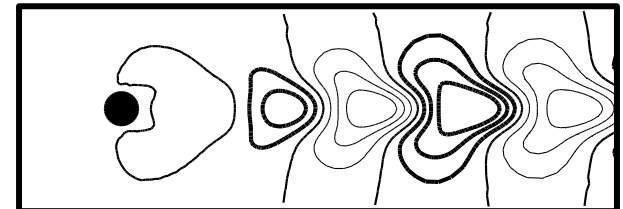
$$\mathbf{u}_1 = \Re \{ \mathbf{f}_1 \}$$



Galerkin approximation

$$\mathbf{u} = \mathbf{u}_s + a_1 \mathbf{u}_1 + a_2 \mathbf{u}_2$$

$$\mathbf{u}_2 = \Im \{ \mathbf{f}_1 \}$$



■ 2-dim. Galerkin model reproduces instability.

Mean-field model

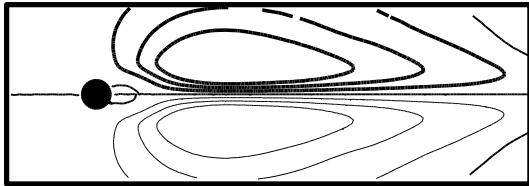
☰ Noack, Afanasiev, Morzyński, Tadmor & Thiele (2003) JFM

Mean-field damping

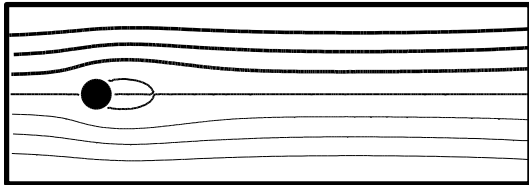
mechanism

☰ Stuart (1958)

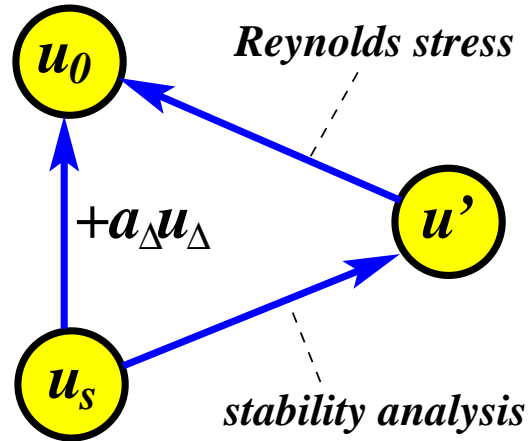
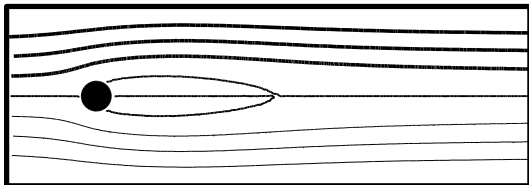
shift mode u_Δ



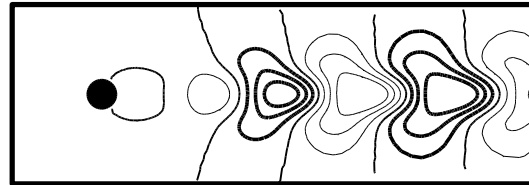
mean flow u_0



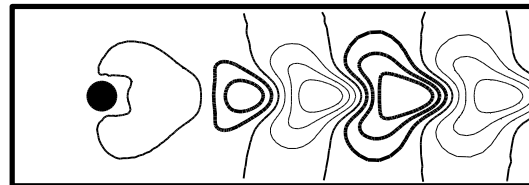
steady solution u_s



eigenmode u_1



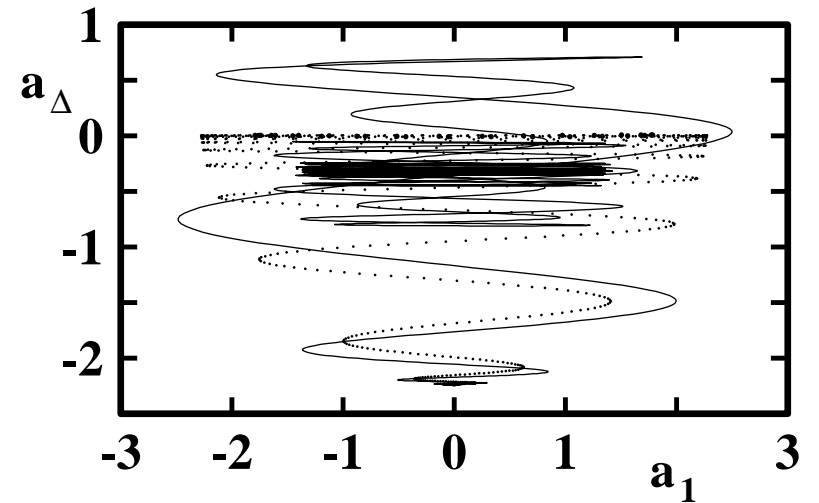
eigenmode u_2



Galerkin approximation

$$u = u_0 + a_\Delta u_\Delta + a_1 u_1 + a_2 u_2$$

Galerkin solution



Fluctuation amplitude
45% too low!

■ Shift mode prevents divergence.

Generalized mean-field model

—  Noack, Afanasiev, Morzyński, Thiele & Tadmor 2003 JFM —

Galerkin model

$$(1a) \mathbf{u} = \mathbf{u}_s + \sum_{i=1}^3 a_i \mathbf{u}_i$$

$$(1b) \frac{da_i}{dt} = \sum_{j=0}^3 l_{ij} a_j + \sum_{j,k=0}^3 q_{ijk} a_j a_k$$

\mathbf{u}_s : steady flow

$\mathbf{u}_{1,2}$: oscillatory modes

\mathbf{u}_3 : shift mode

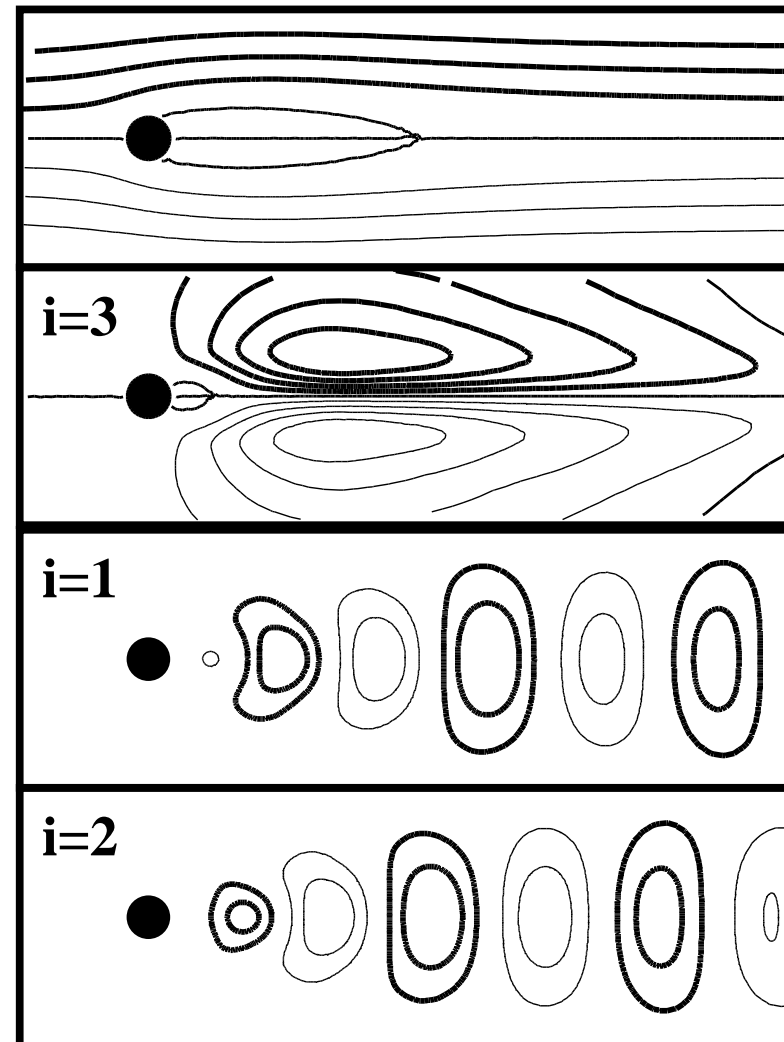
Polar coordinates

$$a_1 = A \cos \phi, \quad a_2 = A \sin \phi$$

$$(2a) \frac{dA}{dt} = (\sigma - \beta a_3) A + h.h.$$

$$(2b) \frac{d\phi}{dt} = (\omega + \gamma a_3) + h.h.$$

$$(2c) \frac{da_3}{dt} = (\sigma_3 a_3 + cA^2) + h.h.$$



Generalized mean-field model

—  Noack, Afanasiev, Morzyński, Thiele & Tadmor 2003 JFM —

Galerkin model

$$(1a) \quad \mathbf{u} = \mathbf{u}_s + \sum_{i=1}^3 a_i \mathbf{u}_i$$

$$(1b) \quad \frac{da_i}{dt} = \sum_{j=0}^3 l_{ij} a_j + \sum_{j,k=0}^3 q_{ijk} a_j a_k$$

\mathbf{u}_s : steady flow

$\mathbf{u}_{1,2}$: oscillatory modes

\mathbf{u}_3 : shift mode

Polar coordinates

$$a_1 = A \cos \phi, \quad a_2 = A \sin \phi$$

$$(2a) \quad \frac{dA}{dt} = (\sigma - \beta a_3) A + h.h.$$

$$(2b) \quad \frac{d\phi}{dt} = (\omega + \gamma a_3) + h.h.$$

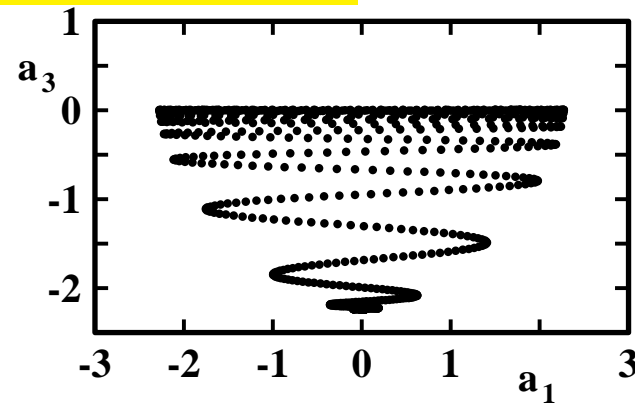
$$(2c) \quad \frac{da_3}{dt} = (\sigma_3 a_3 + cA^2) + h.h.$$

Centre manifold

Using $|\sigma_3| \gg \sigma$ (2c) becomes:

$$0 = (\sigma_3 a_3 + cA^2) \Rightarrow$$

$$(3) \quad a_3 = -\frac{c}{\sigma_3} A^2$$



Landau equations

(3) in (2a,b) yields

$$(4a) \quad \frac{dA}{dt} = \sigma A - \beta^* A^3$$

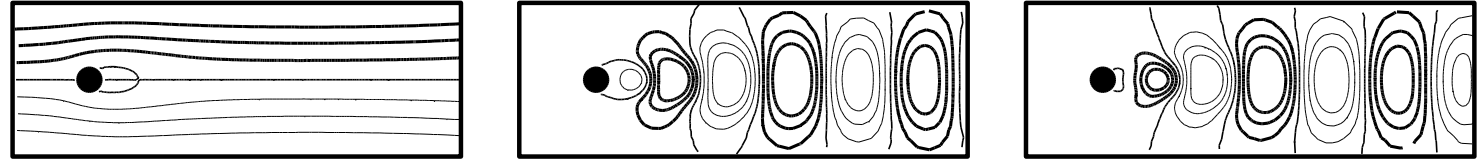
$$(4b) \quad \frac{d\phi}{dt} = \omega + \gamma^* A^2$$

$$\sigma, \omega, \beta^*, \gamma^* > 0$$

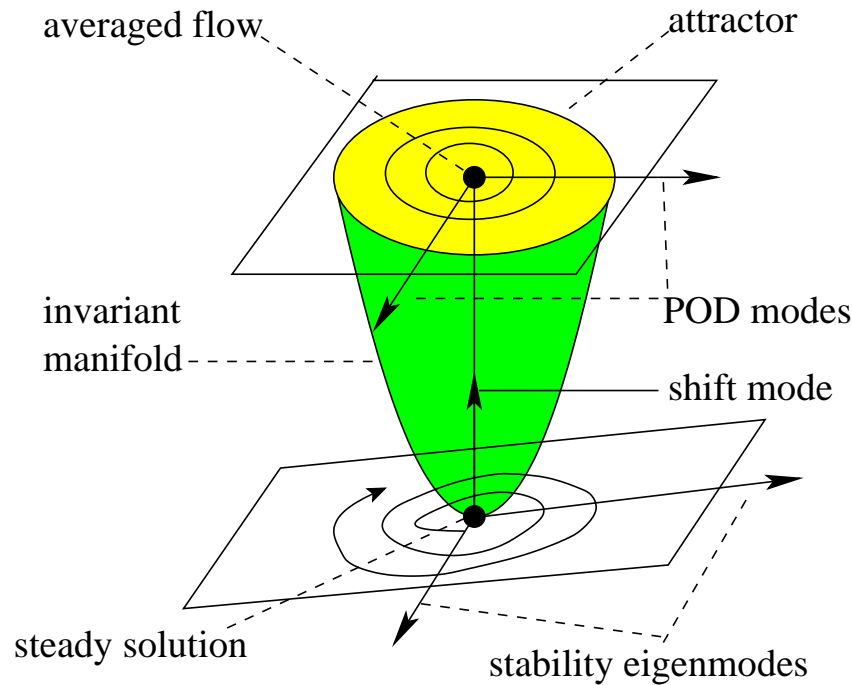
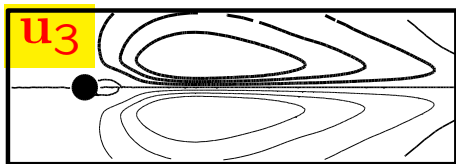
Transient dynamics of wake

☰ Noack, Afanasiev, Morzyński, Tadmor & Thiele (2003) JFM —

Operating
condition II
on attractor



↑
transient
on paraboloid



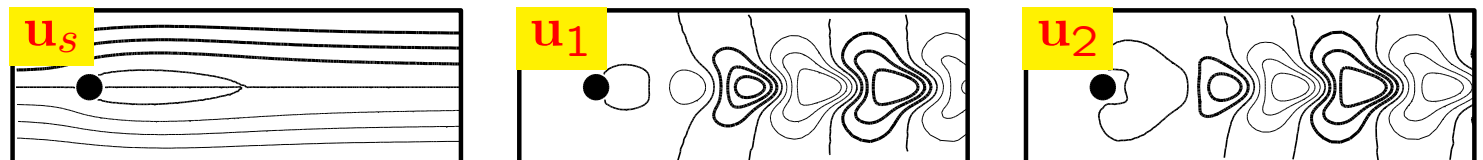
$$\begin{aligned} \frac{d}{dt}a_1 &= \sigma a_1 - \omega a_2 \\ \frac{d}{dt}a_2 &= \sigma a_2 + \omega a_1 \\ \frac{d}{dt}a_3 &= -\sigma_3 a_3 + cA^2 \end{aligned}$$

$$\begin{aligned} \sigma &= \sigma_1 - \beta a_3 \\ \omega &= \omega_1 + \gamma a_3 \\ A^2 &= a_1^2 + a_2^2 \end{aligned}$$

Landau equation

$$\frac{d}{dt}A = \sigma_1 A - \beta^* A^3$$

Operating
condition I
near fixed point



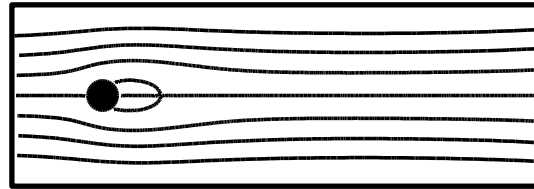
POD Galerkin model

—  Noack, Afanasiev, Morzyński, Tadmor & Thiele (2003) JFM

POD at $Re = 100$

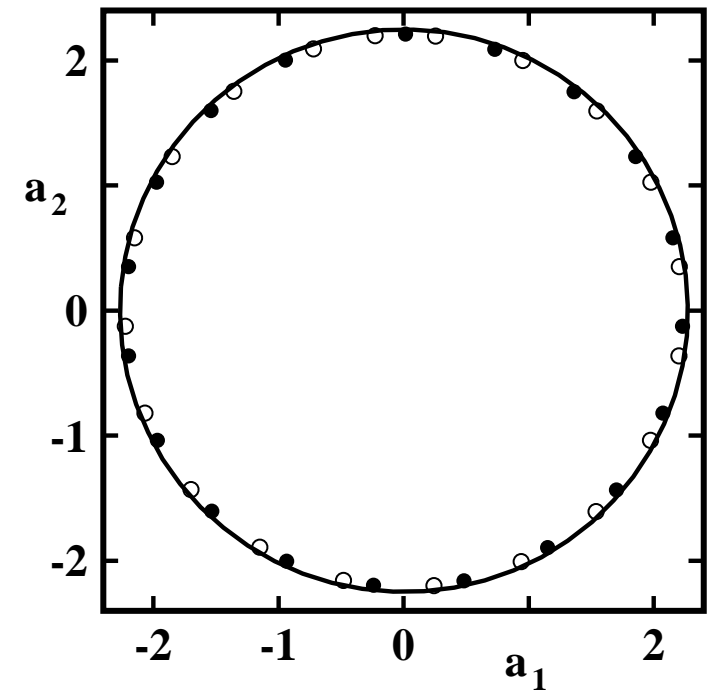
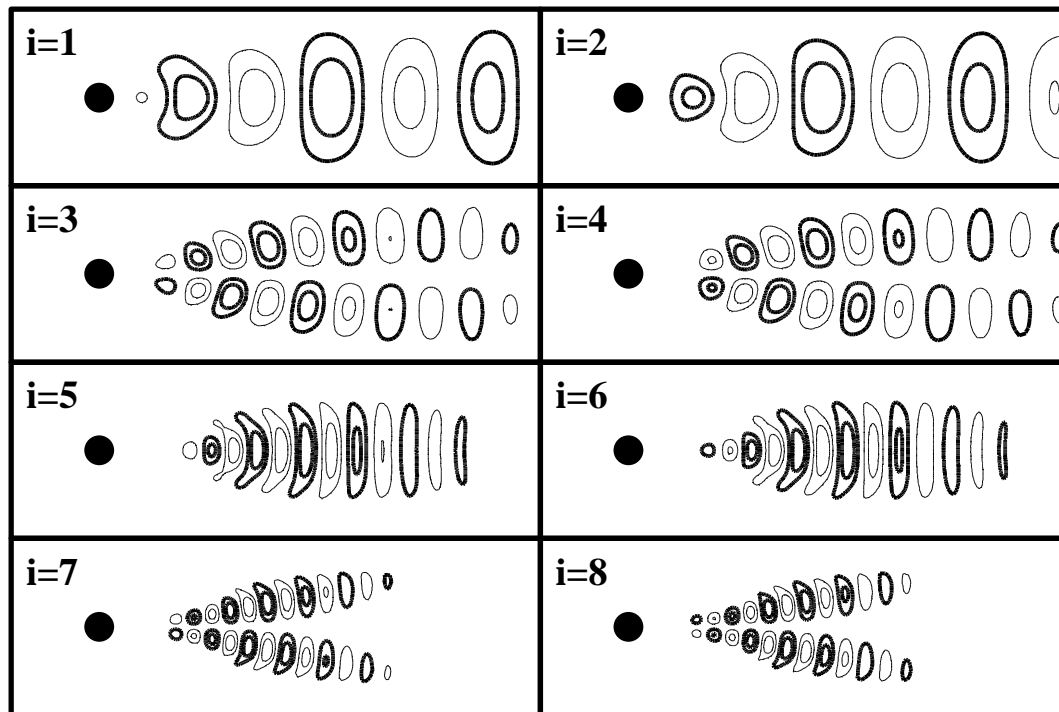
 Deane et al (1991) PF

$$\mathbf{u} = \sum_{i=0}^8 a_i \mathbf{u}_i$$



Galerkin solution

$$\frac{da_i}{dt} = \nu \sum_j l_{ij} a_j + \sum_{j,k} q_{ij} a_j a_k$$



■ 8-dim. POD model reproduces DNS.

POD Galerkin system of cylinder wake II

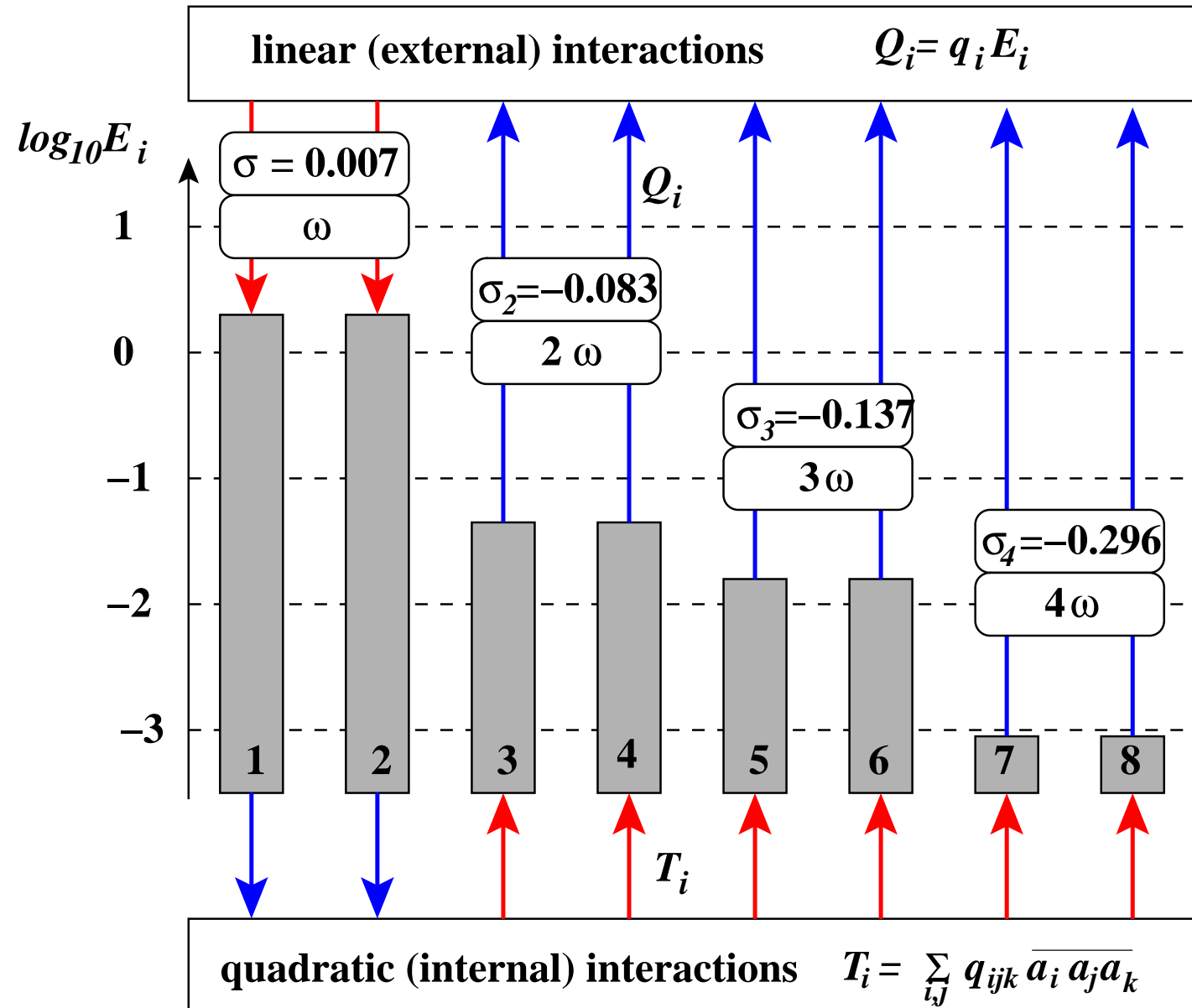
—  Noack, Afanasiev, Morzyński, Thiele & Tadmor 2003 JFM —

Modal

energetics:

$$0 = Q_i + T_i$$

$$Q_i = q_i E_i$$



Structural instability of POD GM — Part I

—  Noack, Afanasiev, Morzyński, Tadmor & Thiele (2003) JFM —

3-dim. SODE ($\mu = 0.1$)

$$\begin{aligned}\frac{du}{dt} &= (\mu - w)u - v \\ \frac{dv}{dt} &= (\mu - w)v + u \\ \frac{dw}{dt} &= -w + (u^2 + v^2)\end{aligned}$$

Unstable fixed point:

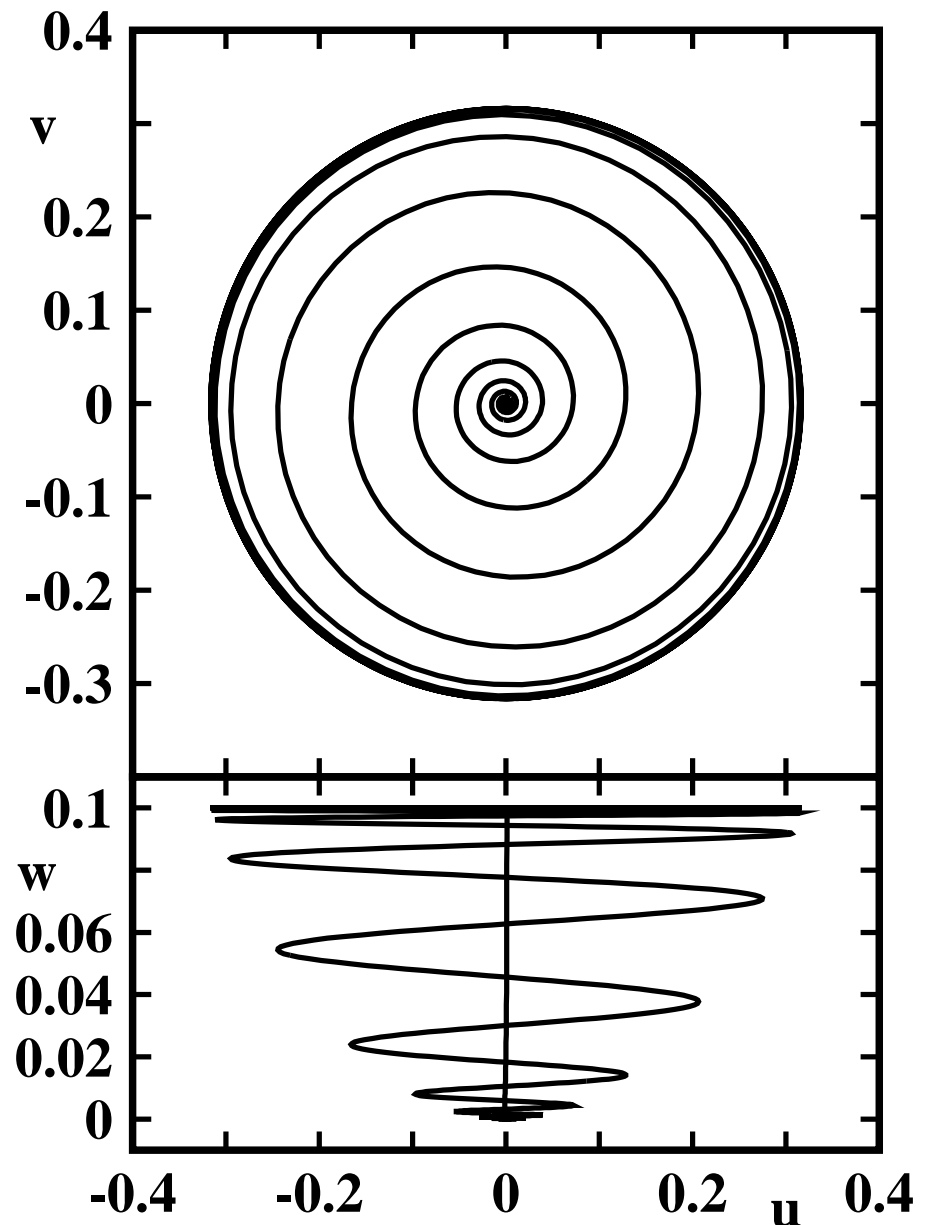
$$u = v = w = 0$$

Stable limit cycle:

$$u = \sqrt{\mu} \cos t$$

$$v = \sqrt{\mu} \sin t$$

$$w = \mu$$



Structural instability of POD GM — Part II

—  Noack, Afanasiev, Morzyński, Tadmor & Thiele (2003) JFM —

POD Galerkin approximation: $\mathbf{u} = \mathbf{u}_0 + a_1 \mathbf{u}_1 + a_2 \mathbf{u}_2$

where $\mathbf{u}_0 = (0, 0, \mu^{\text{Ref}})$, $\mathbf{u}_1 = (1, 0, 0)$, $\mathbf{u}_2 = (0, 1, 0)$

3-dim. SODE ($\mu^{\text{Ref}} = 0.1$)

$$\frac{du}{dt} = (\mu - w) u - v$$

$$\frac{dv}{dt} = (\mu - w) v + u$$

$$\frac{dw}{dt} = -w + (u^2 + v^2)$$

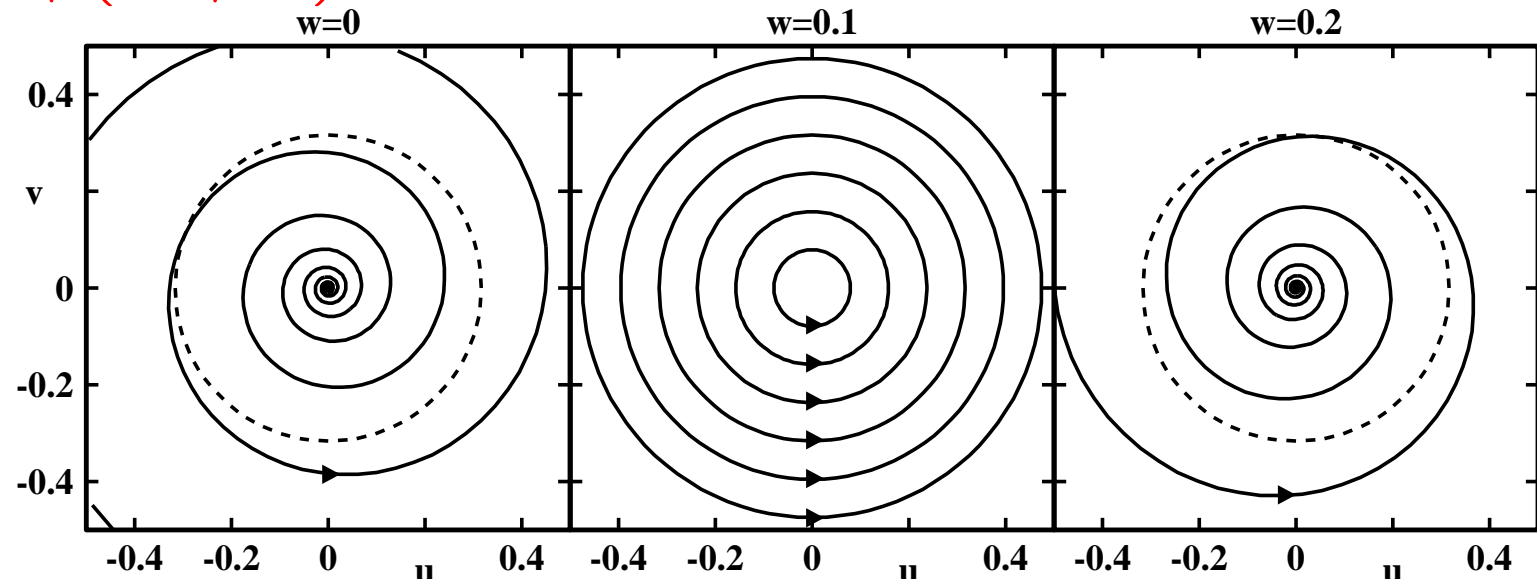
\implies **POD Galerkin system:**

$$\frac{da_1}{dt} = (\mu^{\text{GM}} - \mu^{\text{Ref}}) a_1 - a_2$$

$$\frac{da_2}{dt} = (\mu^{\text{GM}} - \mu^{\text{Ref}}) a_2 + a_1$$

$$\mu^{\text{Ref}} = 0.1$$

Galerkin solutions:

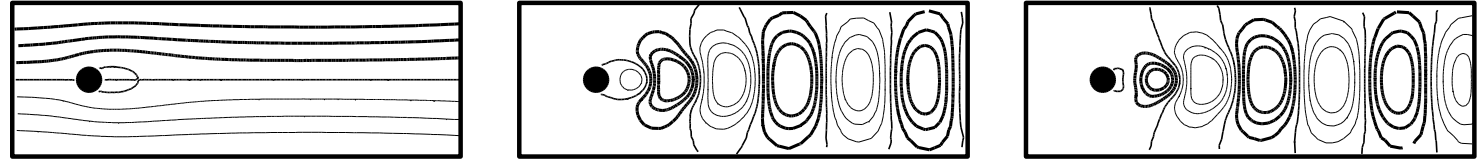


This 'toy' POD GM has all diseases of flow POD GM!

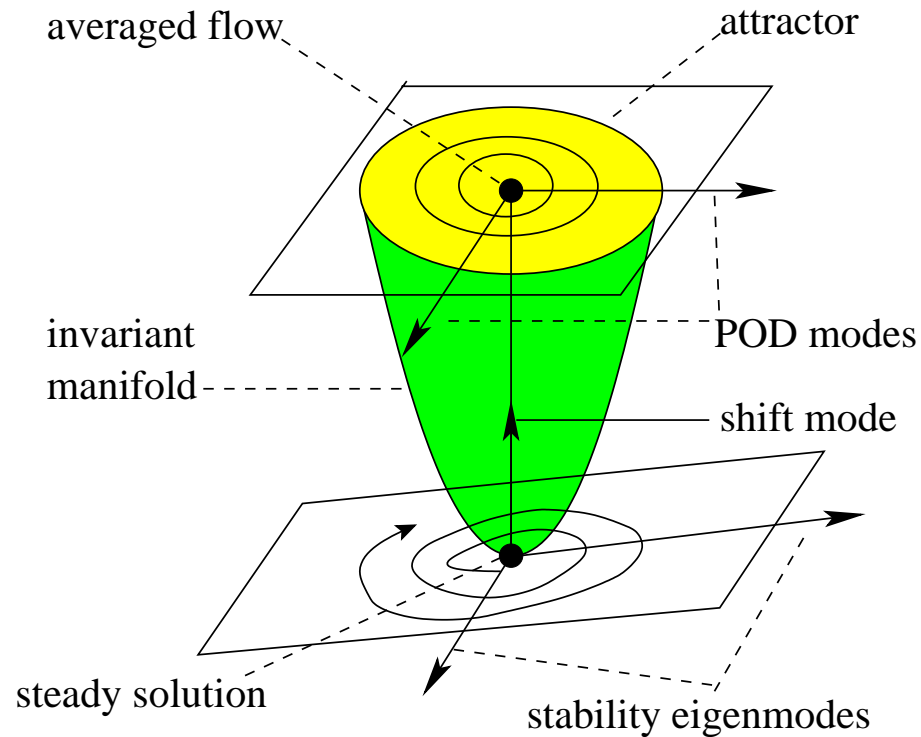
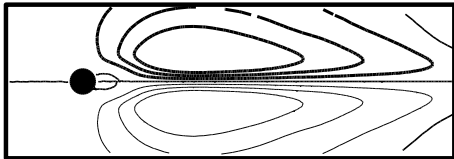
Transient dynamics of wake

☰ Noack, Afanasiev, Morzyński, Tadmor & Thiele (2003) JFM —

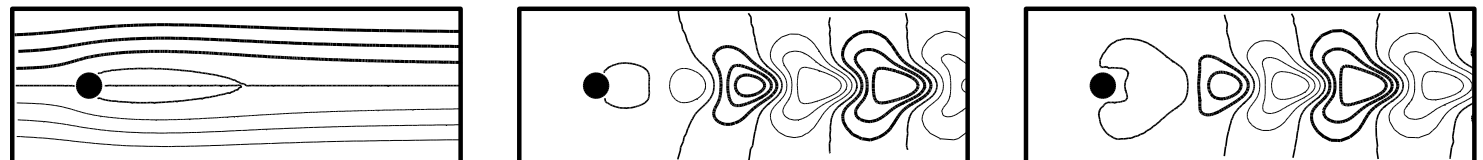
Operating condition II
on attractor



↑
transient
on paraboloid



Operating condition I
near fixed point



Transient dynamics of GM with shift mode

—  Noack, Afanasiev, Morzyński, Tadmor & Thiele (2003) JFM

DNS

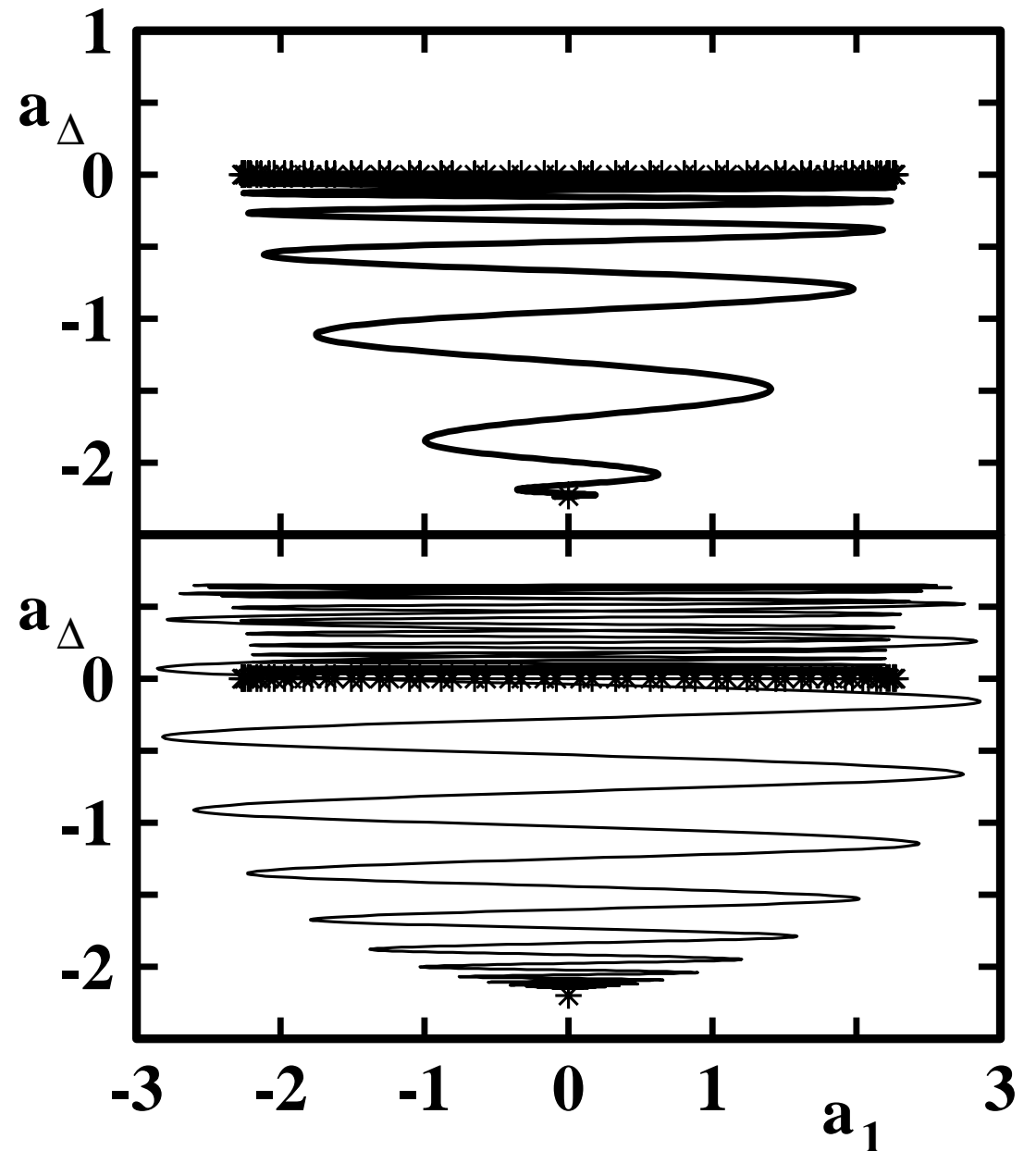
.....

Galerkin model

.....

8 POD modes

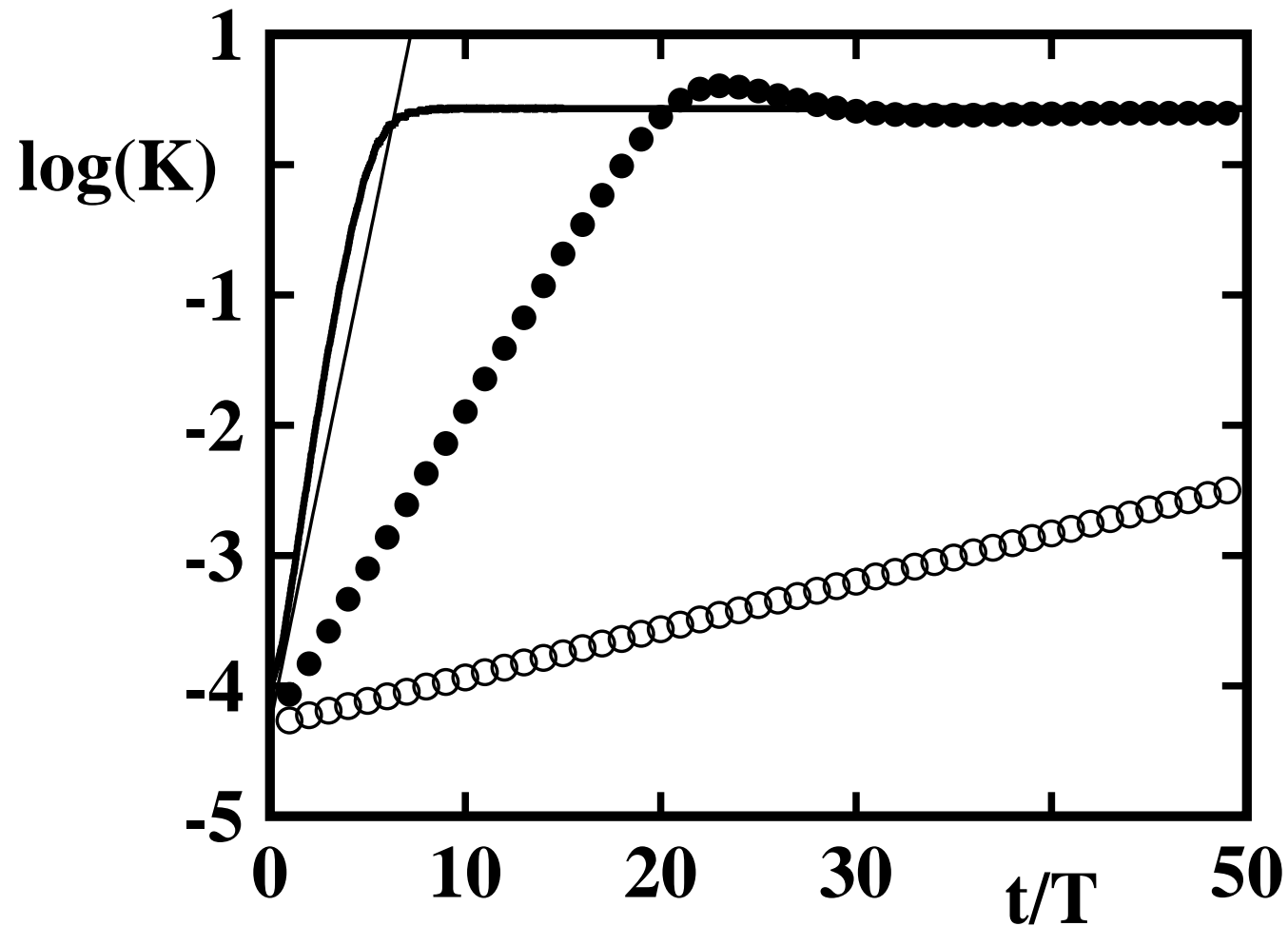
+1 shift mode



Shift mode in POD Galerkin models

—  Noack, Afanasiev, Morzyński, Tadmor & Thiele (2003) JFM —

Transient dynamics



Amplitude selection mechanism

—  Noack, Afanasiev, Morzyński, Tadmor & Thiele (2003) JFM —



(1) Stuart 1958

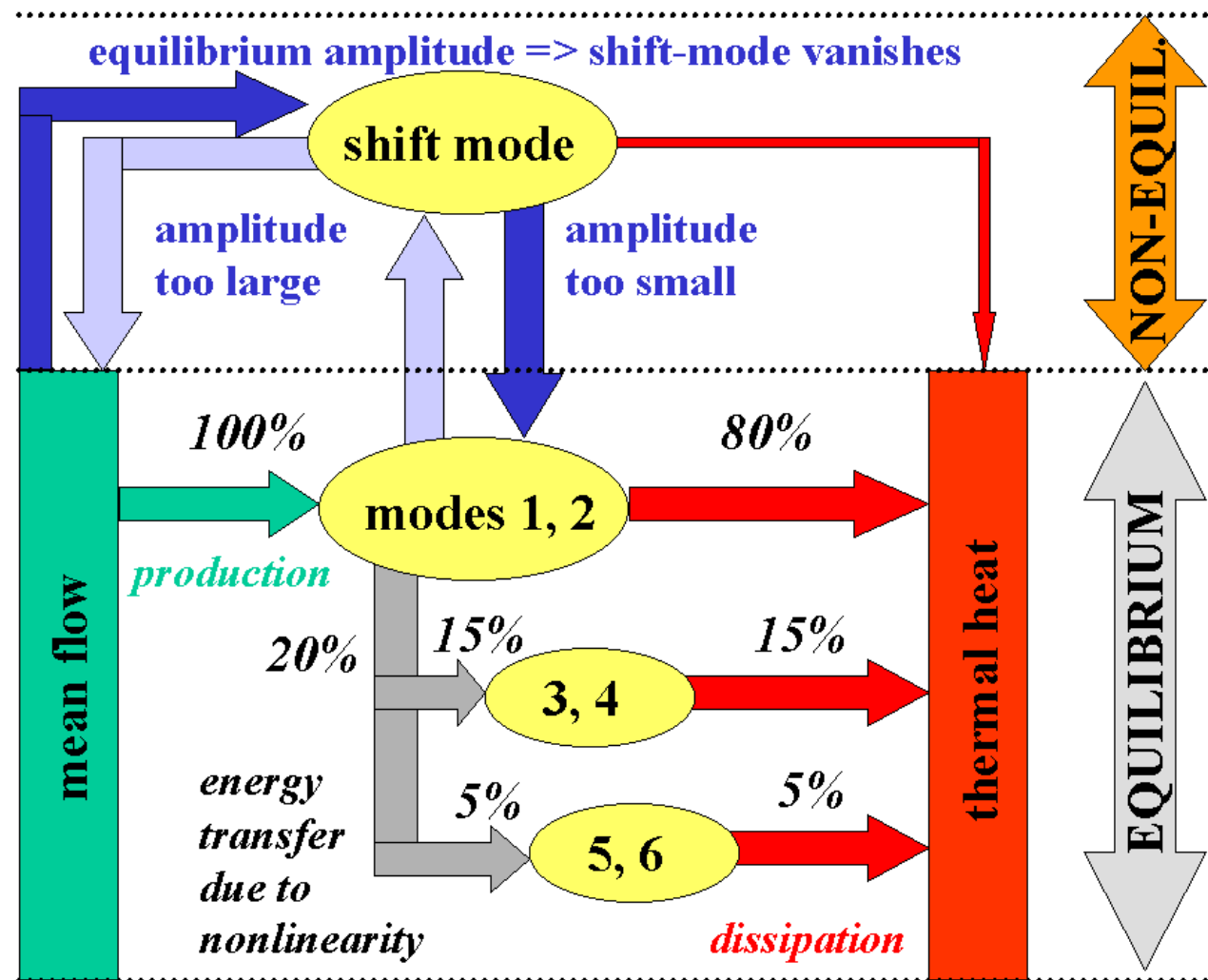
mean-field

theory

(2) \sim K41

energy flow

cascade



Re-dependency of GM with shift mode

—  Noack, Afanasiev, Morzyński, Tadmor & Thiele (2003) JFM —

Strouhal frequency

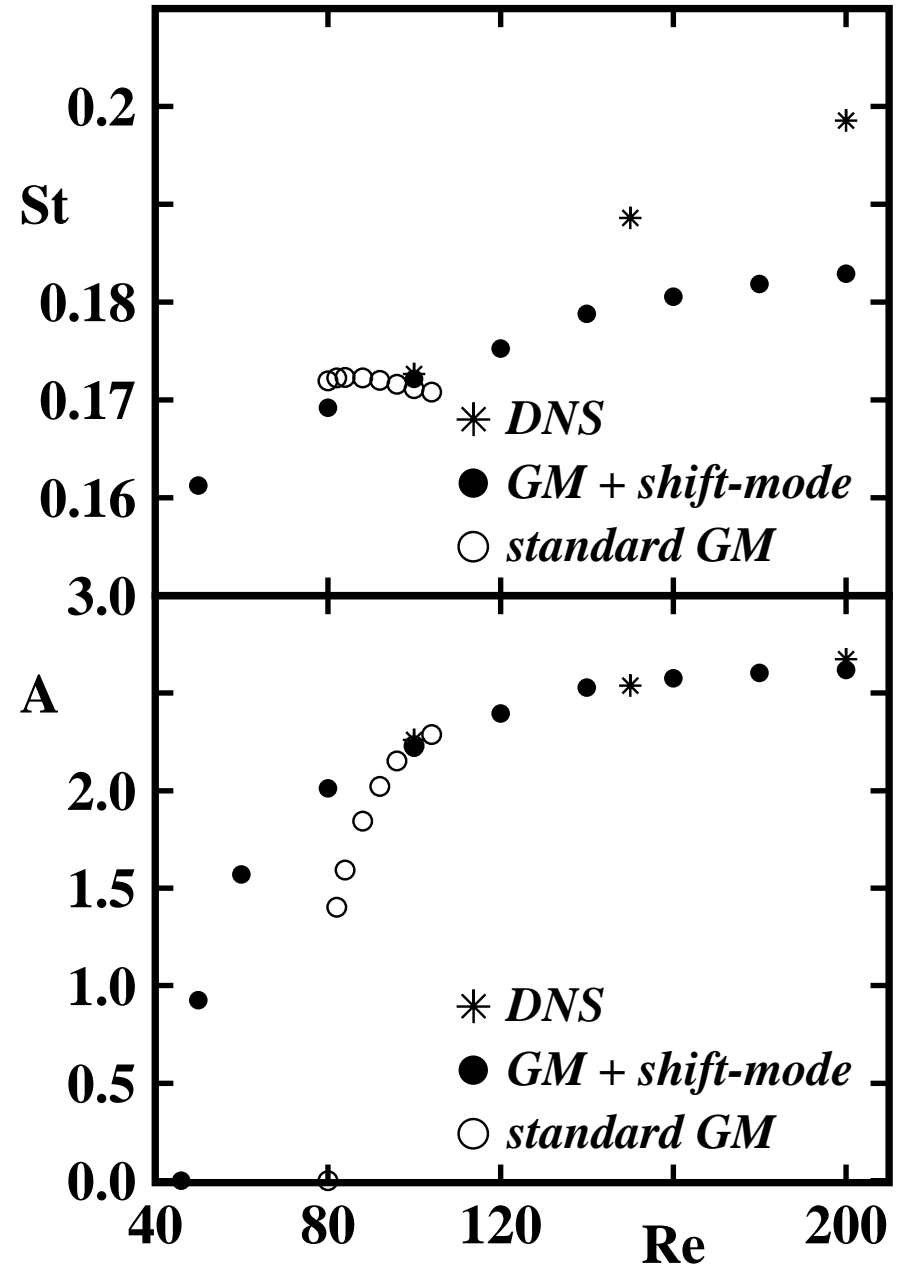
$$St = Uf/D \dots\dots\dots$$

■ Trend $St(Re)$ well predicted with u_{Δ} .

Amplitude

$$K = A^2/2 \dots\dots\dots$$

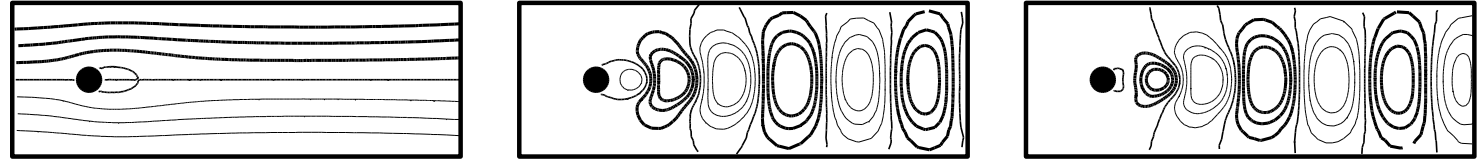
■ Re_{crit} predicted with u_{Δ} .



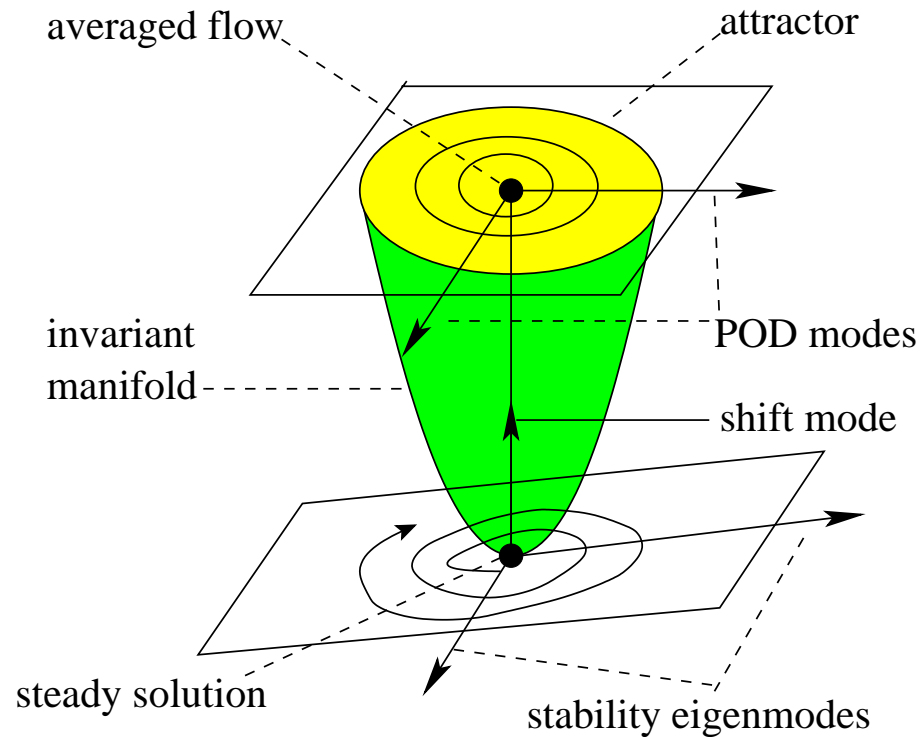
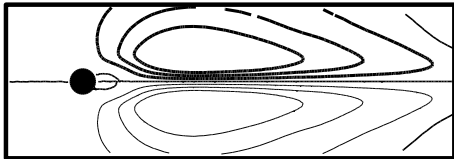
Transient dynamics of wake

☰ Noack, Afanasiev, Morzyński, Tadmor & Thiele (2003) JFM —

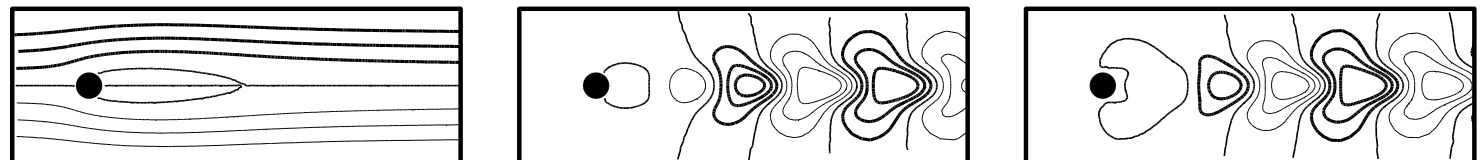
Operating condition II
on attractor



↑
transient
on paraboloid



Operating condition I
near fixed point



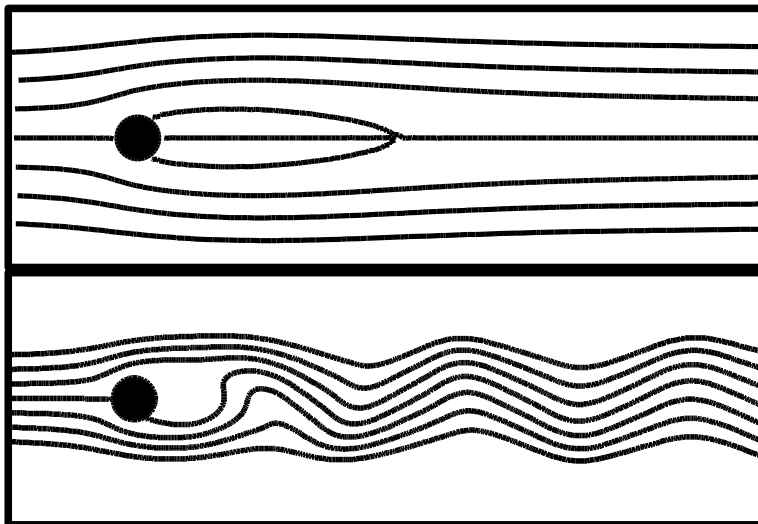
Hybrid GM from POD and mean-field modes

—  Noack, Afanasiev, Morzyński, Tadmor & Thiele (2003) JFM —

$$\begin{array}{ccccccc}
 \mathbf{u} & \rightarrow & \partial_t \mathbf{u} & = & \nu \Delta \mathbf{u} & - \nabla(\mathbf{u}\mathbf{u}) & - \nabla p \\
 \downarrow & & \downarrow & & \downarrow & \downarrow & \downarrow \\
 \mathbf{u} = \sum_{i=0}^8 a_i \mathbf{u}_i & \rightarrow & \frac{da_i}{dt} & = & \nu \sum_{j=0}^{8+3} l_{ij} a_j & + \sum_{j,k=0}^{8+3} (q_{ijk}^c + q_{ijk}^p) a_j a_k \\
 & & & & & & + a_{\Delta} \mathbf{u}_{\Delta} + \sum_{i=1}^2 a_i^* \mathbf{u}_i^* \leftarrow + \text{1st stability eigenmode}
 \end{array}$$

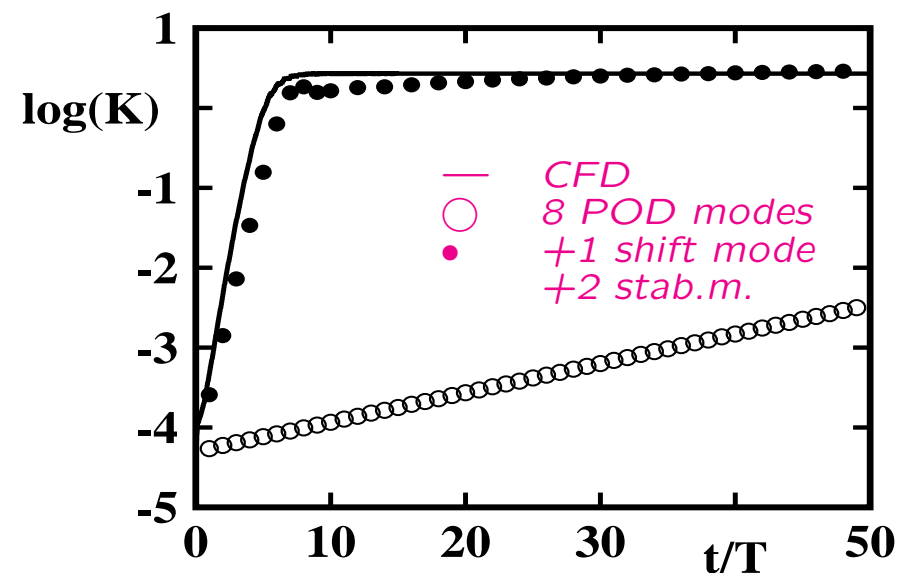
Kinematics

$t = 0 \rightarrow$



$t \geq 7T \rightarrow$

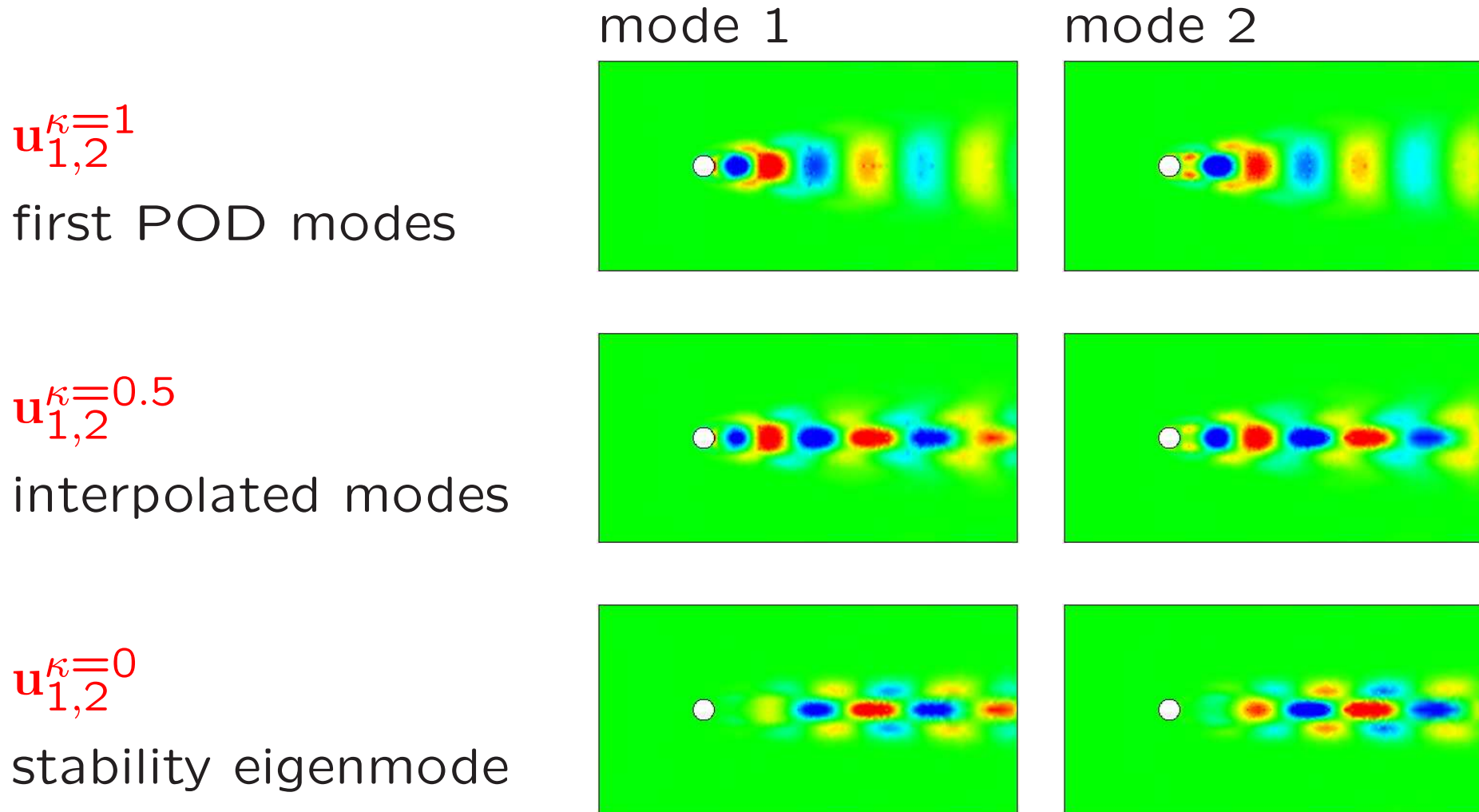
Transient dynamics



Hybrid model resolves natural transients.

Continuous mode interpolation

—  Morzyński, Stankiewicz, Noack, King, Thiele & Tadmor (2006) AFC —



■ **Mode interpolation resolves intermediate states.**

Generalized mean-field model

—  Morzyński, Stankiewicz, Noack, Thiele & Tadmor (2006) AIAA —

3-dim. Galerkin approx.:

Fluctuation energy

for transient

$$\mathbf{u} = \mathbf{u}_B + \mathbf{u}'$$

$$\mathbf{u}_B = \mathbf{u}_s + a_\Delta \mathbf{u}_\Delta$$

$$\mathbf{u}' = a_1^\kappa \mathbf{u}_1^\kappa + a_2^\kappa \mathbf{u}_2^\kappa$$

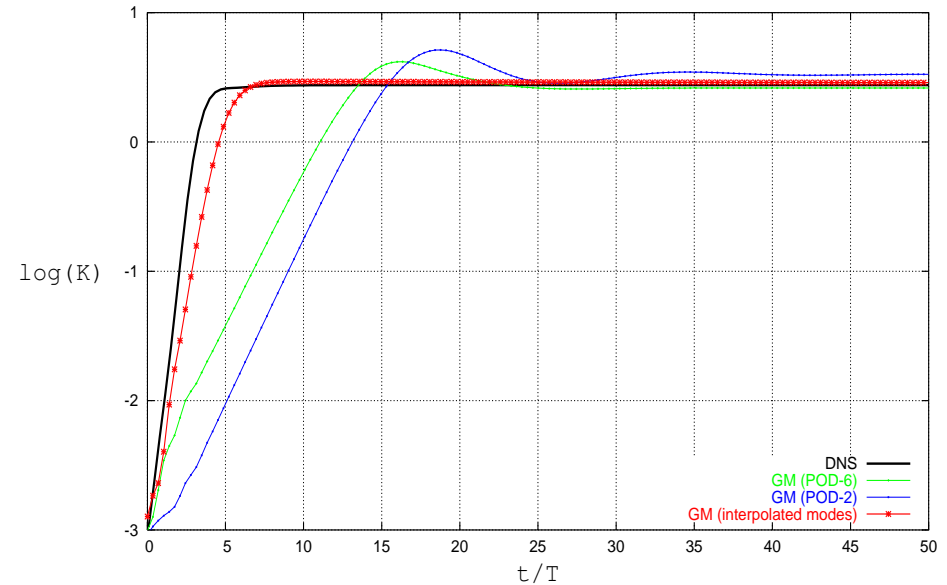
Galerkin system

$$da_1^\kappa/dt = \sigma a_1^\kappa - \omega a_2^\kappa$$

$$da_2^\kappa/dt = \sigma a_2^\kappa + \omega a_1^\kappa$$

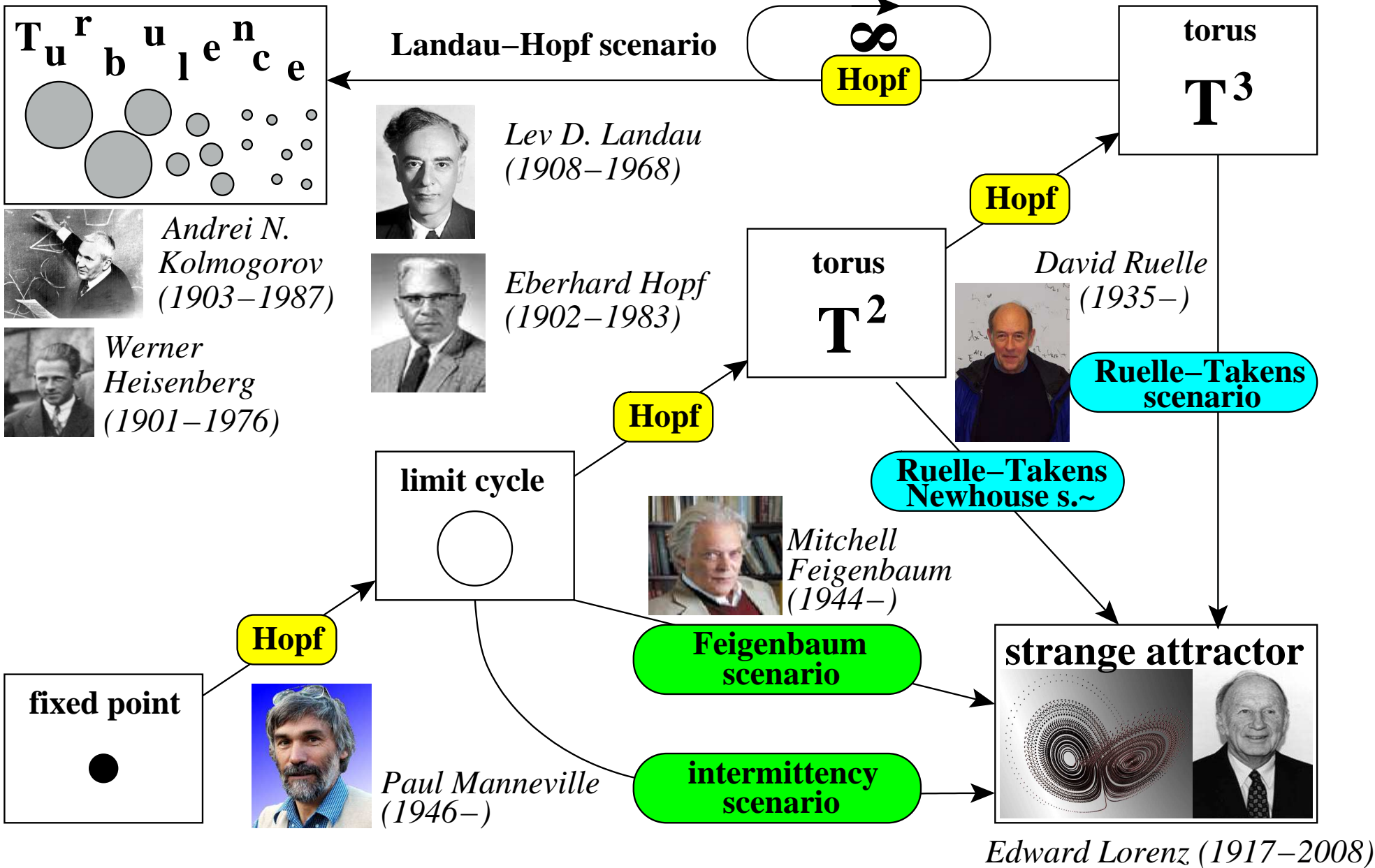
$$da_\Delta/dt = \sigma_D a_\Delta + c \left((a_1^\kappa)^2 + (a_2^\kappa)^2 \right)$$

$$\sigma = \sigma_1 - \beta a_\Delta, \quad \omega = \omega_1 + \gamma a_\Delta, \quad \kappa = a_\Delta / a_\Delta^\infty$$



■ Generalized 3-dim. model $\sim 10\%$ error.

Dream #1: Instabilities \mapsto turbulence



High-lift configuration

☰ *Luchtenburg, Günther, Noack, King & Tadmor (2008) JFM preprint*

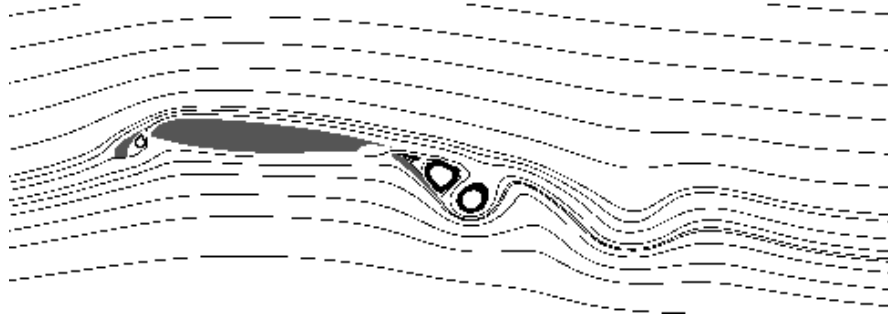
Ask



!

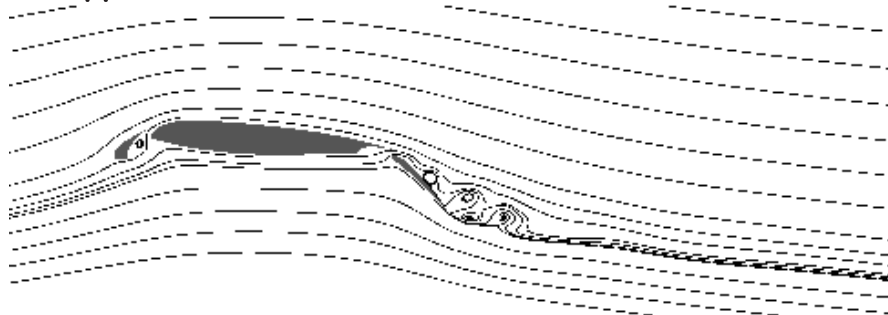
URANS \mapsto natural flow

$$St_{fl}^n = f^n c_{fl} / U_\infty = 0.32$$



actuated flow

$$St_{fl}^a = f^a c_{fl} / U_\infty = 0.6$$

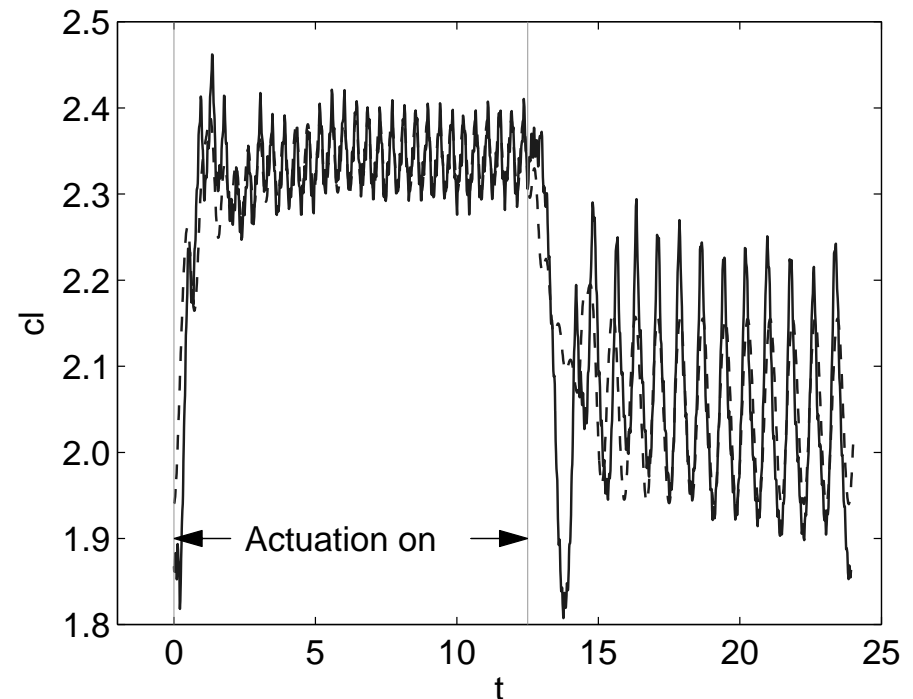


Galerkin model

$$\mathbf{u} = \mathbf{u}_0 + \sum_{i=1}^5 a_i(t) \mathbf{u}_i(\mathbf{x})$$

$$da/dt = f(\mathbf{a}, \mathbf{b}), \quad \mathbf{b} : \text{control}$$

$$c_L = c_L(\mathbf{a}) \text{ lift coefficient}$$



Mean field model can explain ...

■ Transient dynamics

■ Amplitude selection mechanism

(1) dynamics ... **Landau equation** $dA/dt = \sigma A - \beta A^3$;

(2) momentum **Reynolds equation**; $a_{\Delta} = cA^2$;

(3) energetics $dK/dt = P_1 + a_{\Delta}P_2 - D$;

■ Malkus (1958) principle of marginal stability

for the mean flow

■ Structural instability of POD models

... and the need for shift/non-equilibrium modes

■ Many more things:

local linearisation, laminar versus turbulent channel flow,

Questions?
Comments?

Stefan Siegel's
coffee break!